#### On the relationship between data sharpening and Firth's adjusted score function

#### John Braun & Patrick Brown





### Two recipes - each data point is adjusted differently



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Unresolved extensions

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Unresolved extensions

Standard asymptotics - Wand & Jones (1995)

## Data sharpening - Peter Hall

 $Preprocessing \Longrightarrow standard \text{ software (KDE, N-W)}$ 

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Reducing bias & enforcing constraints

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Reduce bias without inflating variance

Preprocessing  $\implies$  standard software (KDE, N-W)

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Reduce bias without inflating variance

No reliance on data greedy alternatives

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DS for derivative estimation?

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Note:  $\hat{f}(x)$ ,  $\hat{g}(x)$  solve score equations

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Binomial logistic regression - adjust the data

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Binomial logistic regression - adjust the data

Cox & Reid (1372), Barndorff-Nielsen. (561), McCullagh and Tibshirani (261), Firth (2337)

$$U^{\star}(\theta) = U(\theta) - i(\theta)b(\theta)$$
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#### Standard: both terms contribute to bias

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Standard: both terms contribute to bias

Nonparametrics: second term is of lower order

$$U^{\star}(\theta) = U(\theta) - i(\theta) \cdot \mathbf{E}\left[\frac{U(\theta)}{i(\theta)}\right]$$

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#### $\boldsymbol{U}$ will be a local likelihood score function

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#### U will be a local likelihood score function

Does this lead to an adjustment of the data?

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$$\mathbf{E}\left[U(\theta_x)\right] \approx -nh^2 \sigma_K^2 \ddot{g}(x)$$

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$$U^{\star}(\theta_x) = U(\theta_x) + nh^2 \sigma_K^2 \ddot{g}(x)$$
  
=  $-2 \sum K_h(X_i - x) \{ Y_i - \theta_x \} + nh^2 \sigma_K^2 \ddot{g}(x)$   
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+  $h^2 \sigma_K^2 \sum K_h(X_i - x) \ddot{g}(X_i)$ 

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 $+ h^{2}\sigma_{K}^{2}\sum K_{h}(X_{i} - x)\ddot{g}(X_{i})$   
=  $-2\sum K_{h}(X_{i} - x)\{Y_{i} - \frac{1}{2}h^{2}\sigma_{K}^{2}\ddot{g}(X_{i}) - \theta_{x}\}$ 

$$\begin{aligned} U^{\star}(\theta_{x}) &= U(\theta_{x}) + nh^{2}\sigma_{K}^{2}\ddot{g}(x) \\ &= -2\sum K_{h}(X_{i} - x)\{Y_{i} - \theta_{x}\} + nh^{2}\sigma_{K}^{2}\ddot{g}(x) \\ &= -2\sum K_{h}(X_{i} - x)\{Y_{i} - \theta_{x}\} \\ &+ h^{2}\sigma_{K}^{2}\sum K_{h}(X_{i} - x)\ddot{g}(X_{i}) \\ &= -2\sum K_{h}(X_{i} - x)\{Y_{i} - \frac{1}{2}h^{2}\sigma_{K}^{2}\ddot{g}(X_{i}) - \theta_{x}\} \\ &= -2\sum K_{h}(X_{i} - x)\{Y_{i}^{\star} - \theta_{x}\} \end{aligned}$$

### **Ideal Data Sharpening**

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Data Sharpening (Hall)

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$$\ell(\theta_x) = \sum K_h(X_i - x)\theta_x - n \int K(u - x)e^{\theta_x} du$$

\*\*

0

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$$U(\theta_{x}) = \sum \{K_{h}(X_{i} - x) - e^{\theta_{x}}\}$$

$$\hat{\theta}_{x} = \log \left[\hat{f}(x)\right] \qquad \hat{f}(x) = \frac{1}{n} \sum K_{h}(X_{i} - x)$$

$$\begin{aligned} X_i &\sim f \qquad \theta_x = f(x) \\ \ell(\theta_x) &= \sum K_h(X_i - x)\theta_x - n \int K(u - x)e^{\theta_x} du \\ U(\theta_x) &= \sum \{K_h(X_i - x) - e^{\theta_x}\} \\ \hat{\theta}_x &= \log \left[ \hat{f}(x) \right] \qquad \hat{f}(x) = \frac{1}{n} \sum K_h(X_i - x) \\ \mathbf{E}[U(\theta_x)] &\approx \frac{1}{2}nh^2 \sigma_K^2 \ddot{f}(x) \end{aligned}$$

$$U^{\star}(\theta_x) = U(\theta_x) - \frac{1}{2}nh^2\sigma_K^2\ddot{f}(x)$$

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=  $\sum \{ K_h(X_i^{\star} - x) - e^{\theta_x} \}$ 

$$X_i^{\star} = X_i + h_s^2 \sigma_K^2 \frac{f(X_i)}{f(X_i)}$$

### Ideal Data Sharpening

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$$\hat{X}_{i}^{\star} = X_{i} + \frac{\sum_{j} K_{h_{s}}(X_{j} - X_{i})(X_{j} - X_{i})}{\sum_{j} K_{h_{s}}(X_{j} - X_{i})}$$

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### Ideal Data Sharpening

$$\hat{X}_{i}^{\star} = X_{i} + \frac{\sum_{j} K_{hs}(X_{j} - X_{i})(X_{j} - X_{i})}{\sum_{j} K_{hs}(X_{j} - X_{i})}$$

$$= \frac{\sum_{j} K_{h_s}(X_j - X_i)X_j}{\sum_{j} K_{h_s}(X_j - X_i)}$$

Data Sharpening (Hall)

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Data Sharpening (Hall)

#### **Proof of concept**

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### **Derivative Estimation**

$$Y_i = g(X_i) + e_i$$
  $\theta_{1x} = g(x), \ \theta_{2x} = \dot{g}(x)$   
 $\ell(g, x) = \sum K_h(X_i - x) \{ Y_i - g(X_i) \}^2$ 

$$\ell(\theta_x) = \sum K_h(X_i - x) \{ Y_i - \theta_{1x} - \theta_{2x}(X_i - x) \}^2$$
$$Y_{i} = g(X_{i}) + e_{i} \qquad \theta_{1x} = g(x), \ \theta_{2x} = \dot{g}(x)$$
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$$\mathbf{E}\left[U(\theta_{2x})\right] \approx -\frac{nh^4\mu_4^K}{3}\ddot{g}(x)$$

$$U^{\star}(\theta_{2x}) = U(\theta_{2x}) + \frac{nh^4\mu_4^K}{3} \ddot{g}(x)$$

$$U^{\star}(\theta_{2x}) = U(\theta_{2x}) + \frac{nh^{\star}\mu_{4}^{\Lambda}}{3} \ddot{g}(x)$$
$$= -2\sum K_{h}(X_{i} - x)(X_{i} - x)Y_{i} + \frac{nh^{4}\mu_{4}^{K}}{3} \ddot{g}(x)$$

1 K

$$U^{\star}(\theta_{2x}) = U(\theta_{2x}) + \frac{nh^{4}\mu_{4}^{\Lambda}}{3} \ddot{g}(x)$$
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$$= -2\sum K_{h}(X_{i} - x)(X_{i} - x)Y_{i}$$

1 12

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=  $-2\sum K_{h}(X_{i} - x)(X_{i} - x)Y_{i}$   
 $+ \frac{h^{2}\mu_{4}^{K}}{3\sigma_{K}^{2}}\sum K_{h}(X_{i} - x)(X_{i} - x)\ddot{g}(X_{i})$ 

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+  $\frac{h^{2}\mu_{4}^{K}}{3\sigma_{K}^{2}}\sum K_{h}(X_{i} - x)(X_{i} - x)\ddot{g}(X_{i})$   
=  $-2\sum K_{h}(X_{i} - x)(X_{i} - x)\left\{Y_{i} - \frac{h^{2}\mu_{4}^{K}}{6\sigma_{K}^{2}}\ddot{g}(X_{i})\right\}$ 

1 12

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=  $-2\sum K_{h}(X_{i} - x)(X_{i} - x)\left\{Y_{i} - \frac{h^{2}\mu_{4}^{K}}{6\sigma_{K}^{2}}\ddot{g}(X_{i})\right\}$   
=  $-2\sum K_{h}(X_{i} - x)(X_{i} - x)Y_{i}^{\star}$ 

$$Y_i^{\star} = Y_i - \frac{h^2 \mu_4^K}{6\sigma_K^2} \ddot{g}(X_i)$$

## Ideal Data Sharpening

$$Y_i^{\star} = Y_i - \frac{\hbar^2 \mu_4^K}{6\sigma_K^2} \ddot{g}(X_i)$$

Ideal Data Sharpening

$$\widehat{Y}_{i}^{\star} = Y_{i} - rac{\mu_{4}^{K}}{3\sigma_{K}^{4}} [\widehat{g}(X_{i}) - Y_{i}]$$
 Data Sharpening (BBS)

$$Y_i^{\star} = Y_i - \frac{\hbar^2 \mu_4^K}{6\sigma_K^2} \ddot{g}(X_i)$$
 Ideal Data Sharpening  
 $\hat{Y}_i^{\star} = Y_i - \frac{\mu_4^K}{3\sigma_K^4} [\hat{g}(X_i) - Y_i]$  Data Sharpening (BBS)

## Nadaraya-Watson Estimator

$$Y_i^{\star} = Y_i - \frac{\hbar^2 \mu_4^K}{6\sigma_K^2} \ddot{g}(X_i)$$
 Ideal Data Sharpening  
 $\hat{Y}_i^{\star} = Y_i - \frac{\mu_4^K}{3\sigma_K^4} [\hat{g}(X_i) - Y_i]$  Data Sharpening (BBS)

## Nadaraya-Watson Estimator

 $Y_i^{\star} = Y_i - \frac{1}{2}h^2 \sigma_K^2 \ddot{g}(X_i)$  Ideal Data Sharpening

$$Y_i^{\star} = Y_i - \frac{\hbar^2 \mu_4^K}{6\sigma_K^2} \ddot{g}(X_i)$$
 Ideal Data Sharpening  
 $\hat{Y}_i^{\star} = Y_i - \frac{\mu_4^K}{3\sigma_K^4} [\hat{g}(X_i) - Y_i]$  Data Sharpening (BBS)

## Nadaraya-Watson Estimator

- $Y_i^{\star} = Y_i \frac{1}{2}h^2 \sigma_K^2 \ddot{g}(X_i)$  Ideal Data Sharpening
- $\widehat{Y}_i^{\star} = Y_i [\widehat{g}(X_i) Y_i]$  Data Sharpening (Hall)

## Gas mileage Y as a function g of cruising speed X

# Gas mileage Y as a function g of cruising speed X Where does the first derivative $\dot{g}$ equal zero?

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Usual local linear derivative estimate versus

Gas mileage Y as a function g of cruising speed XWhere does the first derivative  $\dot{g}$  equal zero? Usual local linear derivative estimate versus Sharpened counterpart Gas mileage Y as a function g of cruising speed XWhere does the first derivative  $\dot{g}$  equal zero? Usual local linear derivative estimate versus Sharpened counterpart

Data:

Gas mileage Y as a function g of cruising speed XWhere does the first derivative  $\dot{g}$  equal zero? Usual local linear derivative estimate versus Sharpened counterpart Data: 15 observations of gas mileage Gas mileage Y as a function g of cruising speed XWhere does the first derivative  $\dot{g}$  equal zero?

Usual local linear derivative estimate versus

Sharpened counterpart

Data:

15 observations of gas mileage Equally spaced cruising speeds [5,75]

## **Fuel Efficiency**

## Model:

$$g(x) = 25\sin(x/30) + 5 + e$$

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## Optimal speed is 47.12 & 1000 samples

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# Optimal speed is 47.12 & 1000 samples Standard: Bias of 9.79 & root MSE of 11.41 Sharpened: Bias of 6.41 & root MSE of 7.92

#### **Derivative estimation**

Firth's adjusted score function ideal vehicle

#### Derivative estimation

Firth's adjusted score function ideal vehicle

Higher order derivatives

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## Higher order derivatives

Complex coefficients & residuals from higher order polynomial fits

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Clear how to "ideally" sharpen the data

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#### Derivatives in a multivariate setting (spatial) A single adjustment may/will not bias correct in all directions

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## Derivatives in a multivariate setting (spatial)

A single adjustment may/will not bias correct in all directions Consider a very regular grid
# Expanding the boundaries of DS

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## Derivatives in a multivariate setting (spatial)

A single adjustment may/will not bias correct in all directions Consider a very regular grid Consider a single direction